



0.25 MOD
Similar to 96DP



0.3 MOD
Similar to 80DP



0.35 MOD
Similar to 72DP



0.4 MOD
Similar to 64DP



0.5 MOD
Similar to 48DP



0.6 MOD
Similar to 40DP



0.8 MOD
Similar to 32DP



1 MOD
Similar to 24DP



1.25 MOD
Similar to 20DP



1.5 MOD
Similar to 16DP



2 MOD
Similar to 12DP



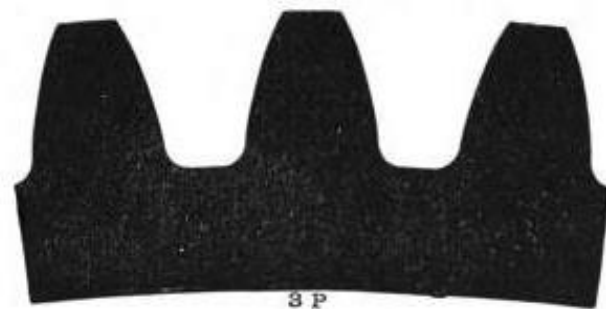
2.5 MOD
Similar to 10DP



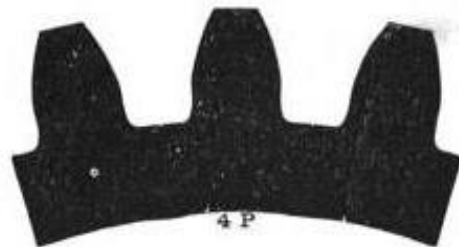
3 MOD
Similar to 8DP



4 MOD
Similar to 6DP



3 P



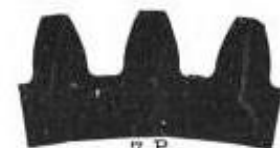
4 P



5 P



6 P



7 P



8 P



20 P



18 P



16 P



14 P



12 P

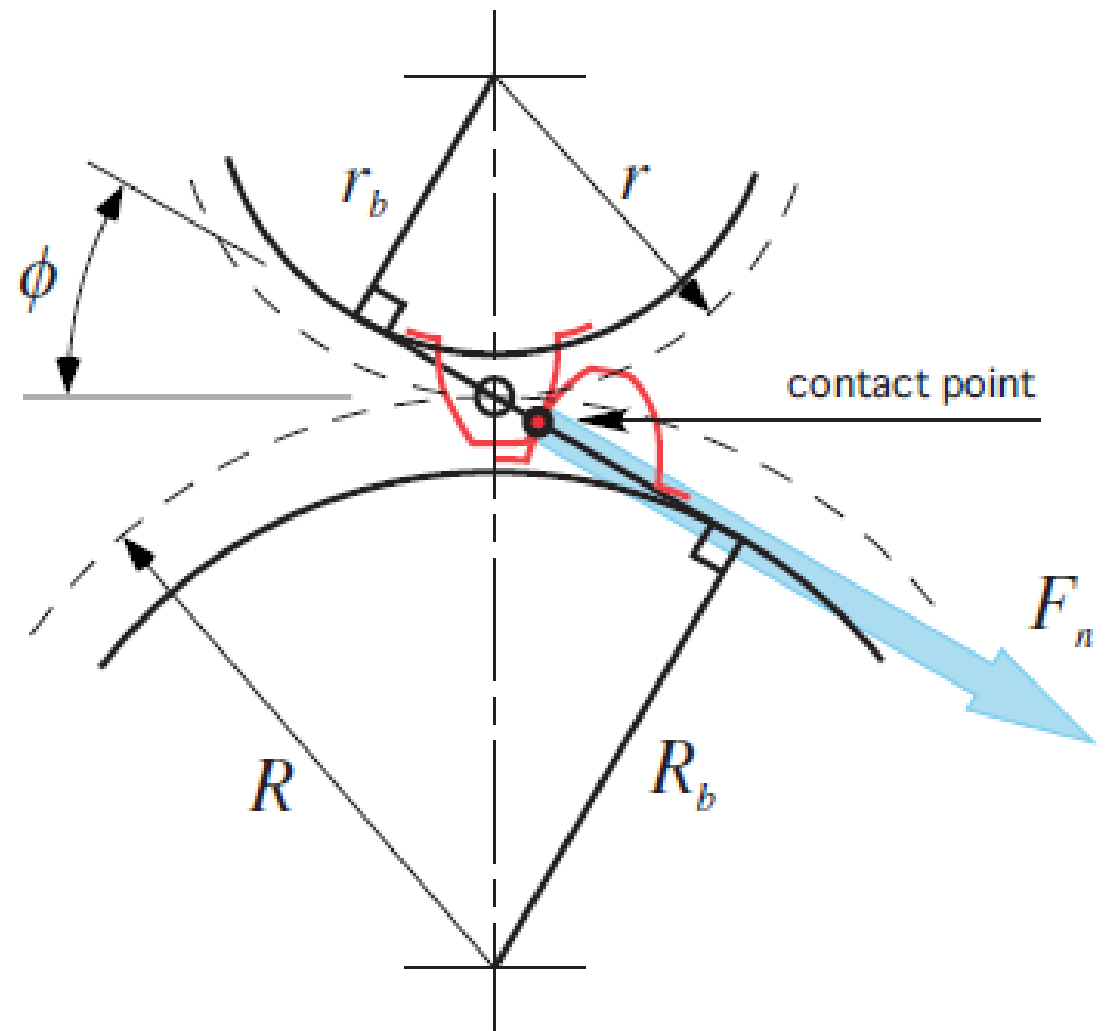
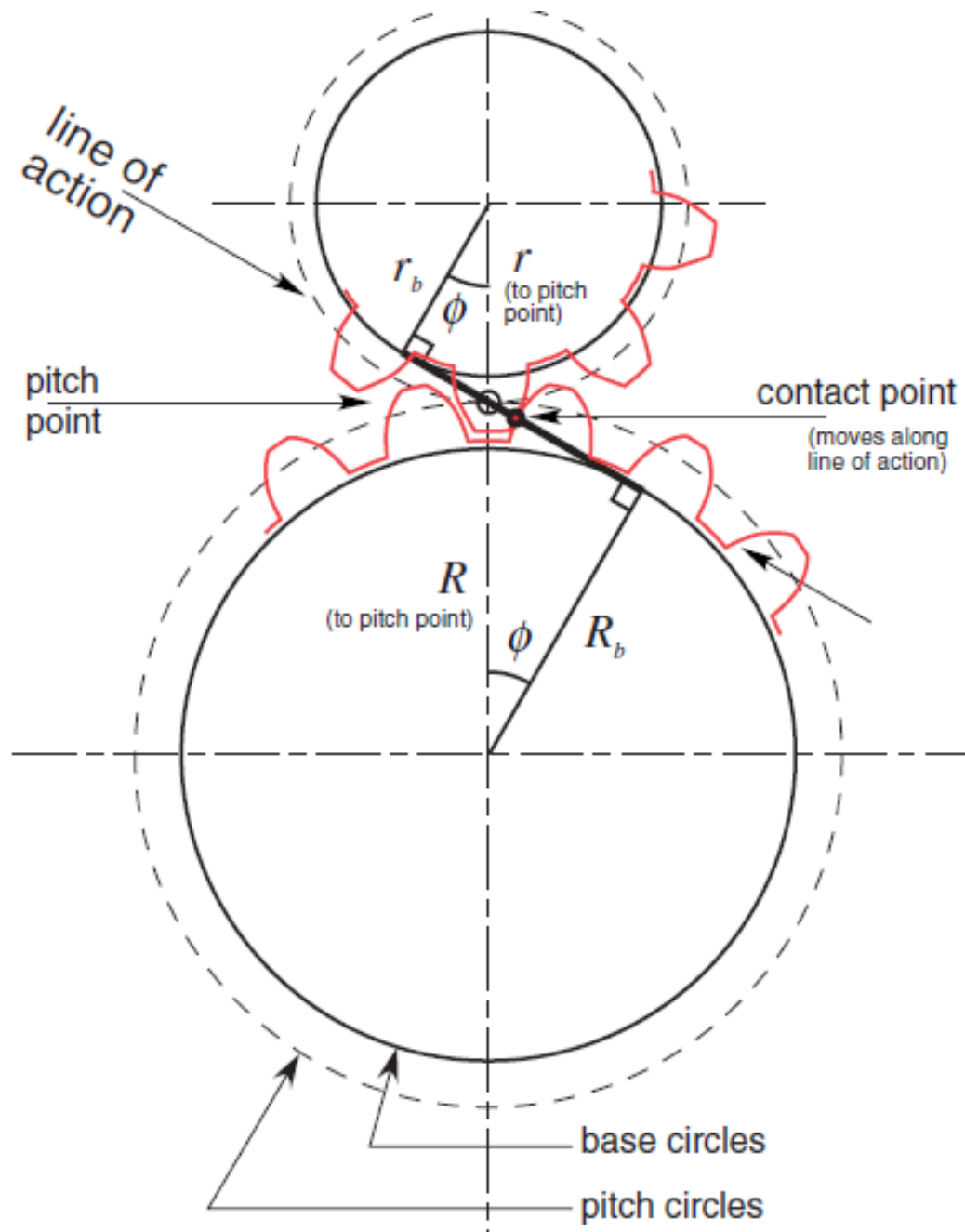


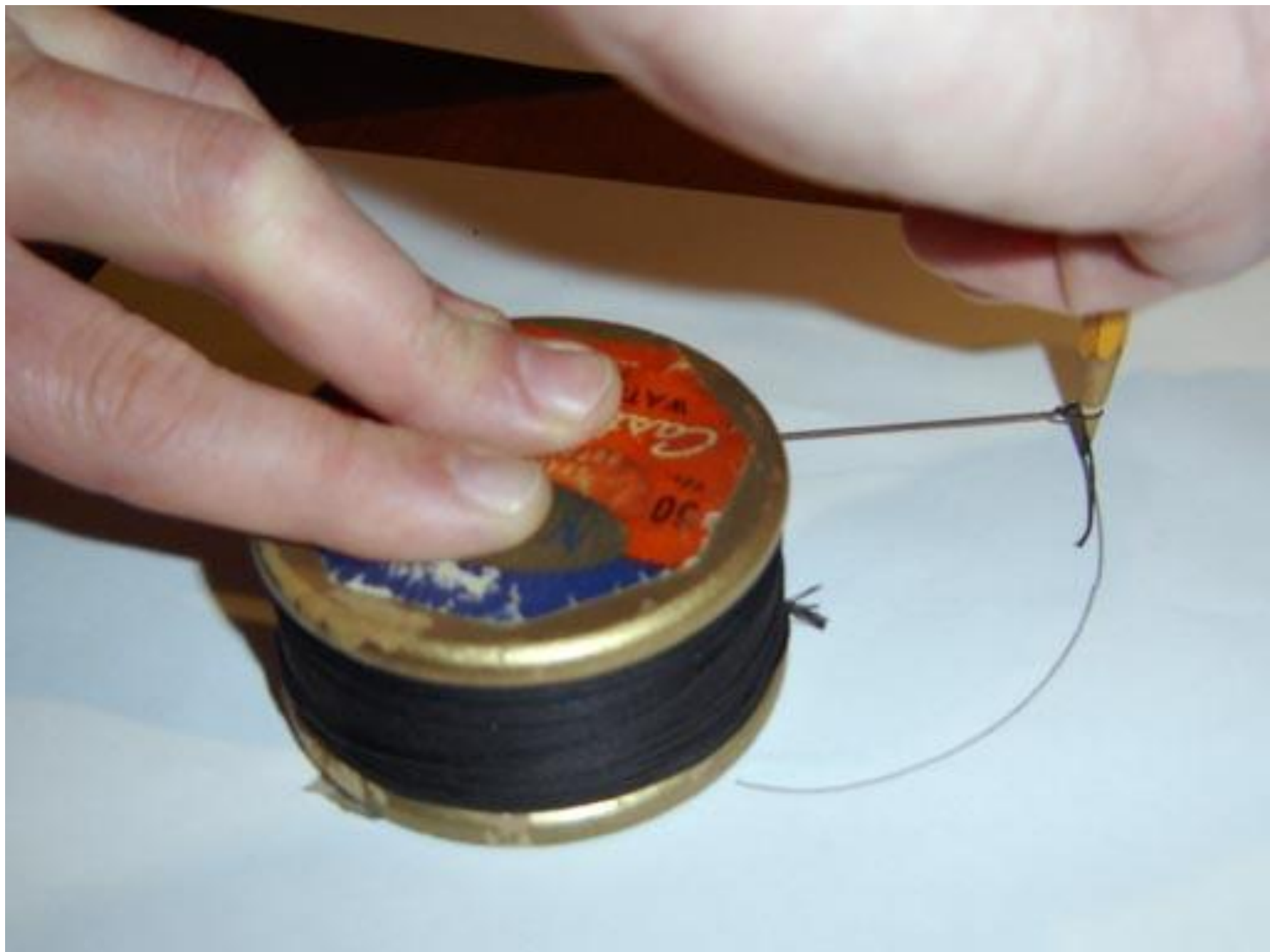
10 P

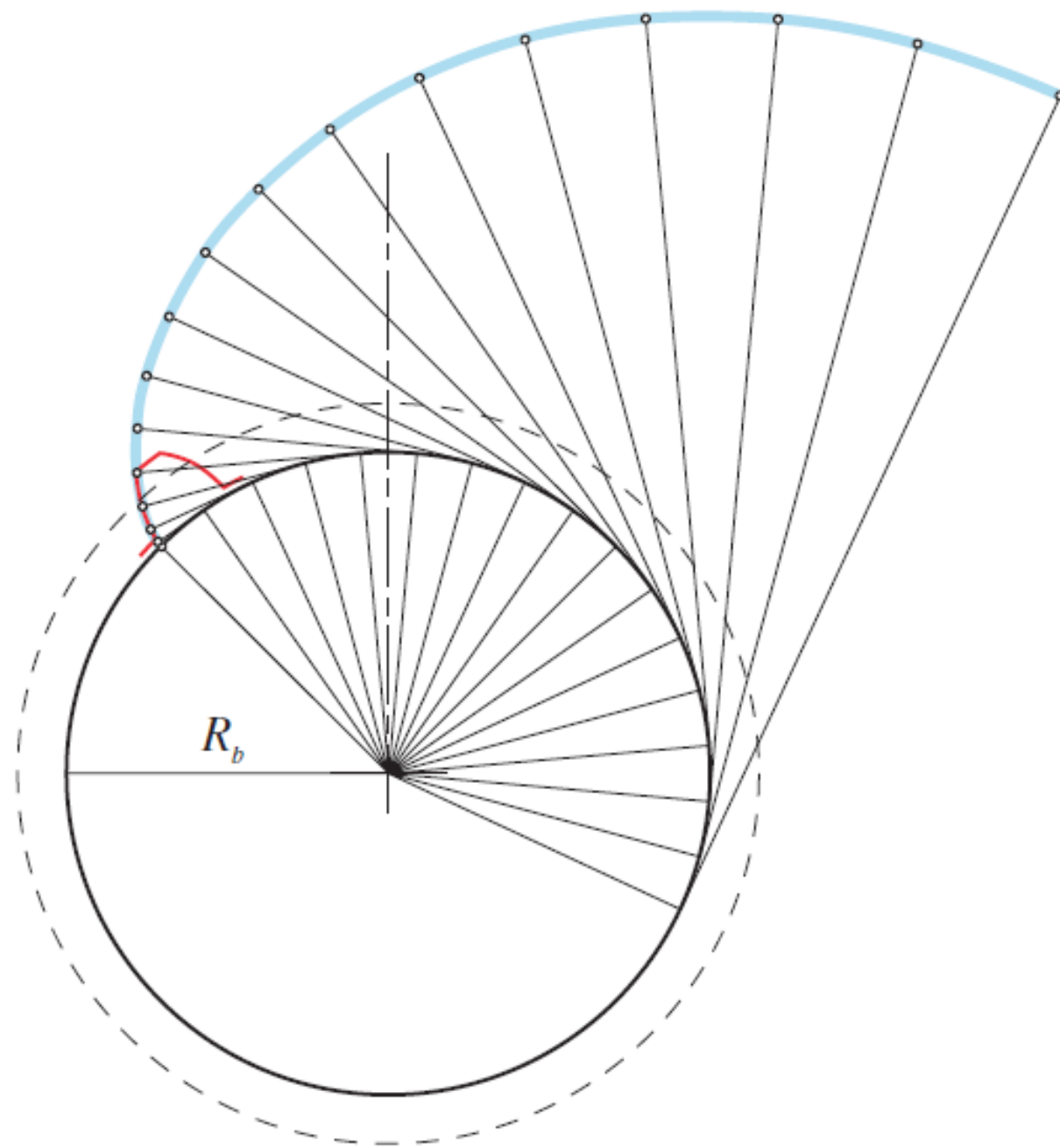


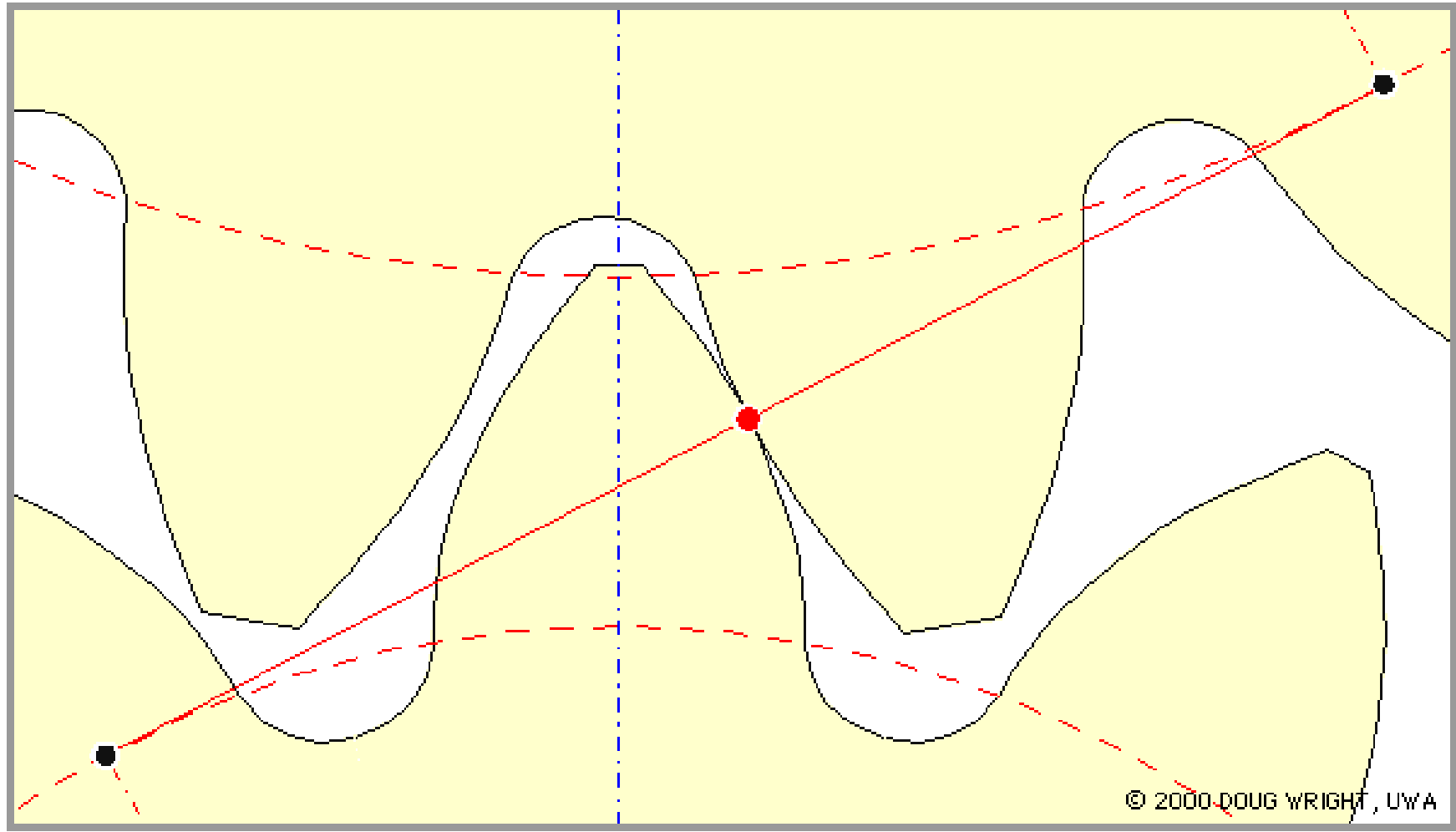
9 P

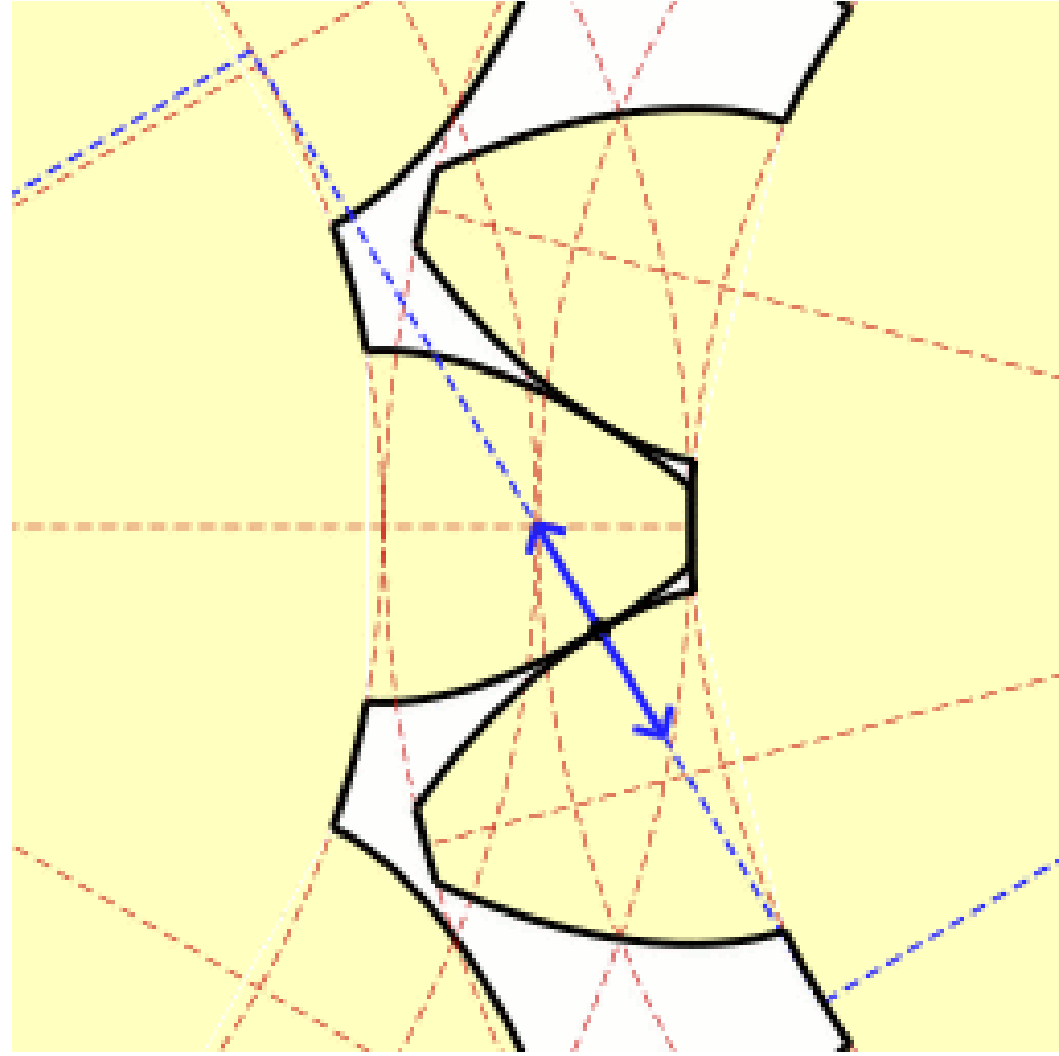












J, K : Initial & final points of contacts

L, M : Points of tangency of line of action with base circles

Z : Length of line of action

$$Z = \overline{JK} = \overline{JP} + \overline{PK} \quad (1)$$

$$\overline{JP} = \overline{JM} - \overline{PM} \quad (2)$$

Consider the two triangles on pinion side: BMJ & BMP .

From triangle BMJ :

$$\overline{JM} = \sqrt{\overline{BJ}^2 - \overline{BM}^2} = \sqrt{(r_p + a_p)^2 - (r_p \cos \phi)^2} \quad (3)$$

From triangle BMP :

$$\overline{PM} = \overline{BP} \sin \phi = r_p \sin \phi \quad (4)$$

Substitute (3) & (4) in (2):

$$\overline{JP} = \sqrt{(r_p + a_p)^2 - (r_p \cos \phi)^2} - r_p \sin \phi \quad (5)$$

Similar procedure on gear side. Consider triangles: ALK & ALP will result in:

$$\overline{PK} = \sqrt{(r_g + a_g)^2 - (r_g \cos \phi)^2} - r_g \sin \phi \quad (6)$$

$$\text{Noting that } a_p = a_g = a \text{ and } (r_p + r_g) = C \quad (7)$$

Substituting (5), (6), and (7) in (1):

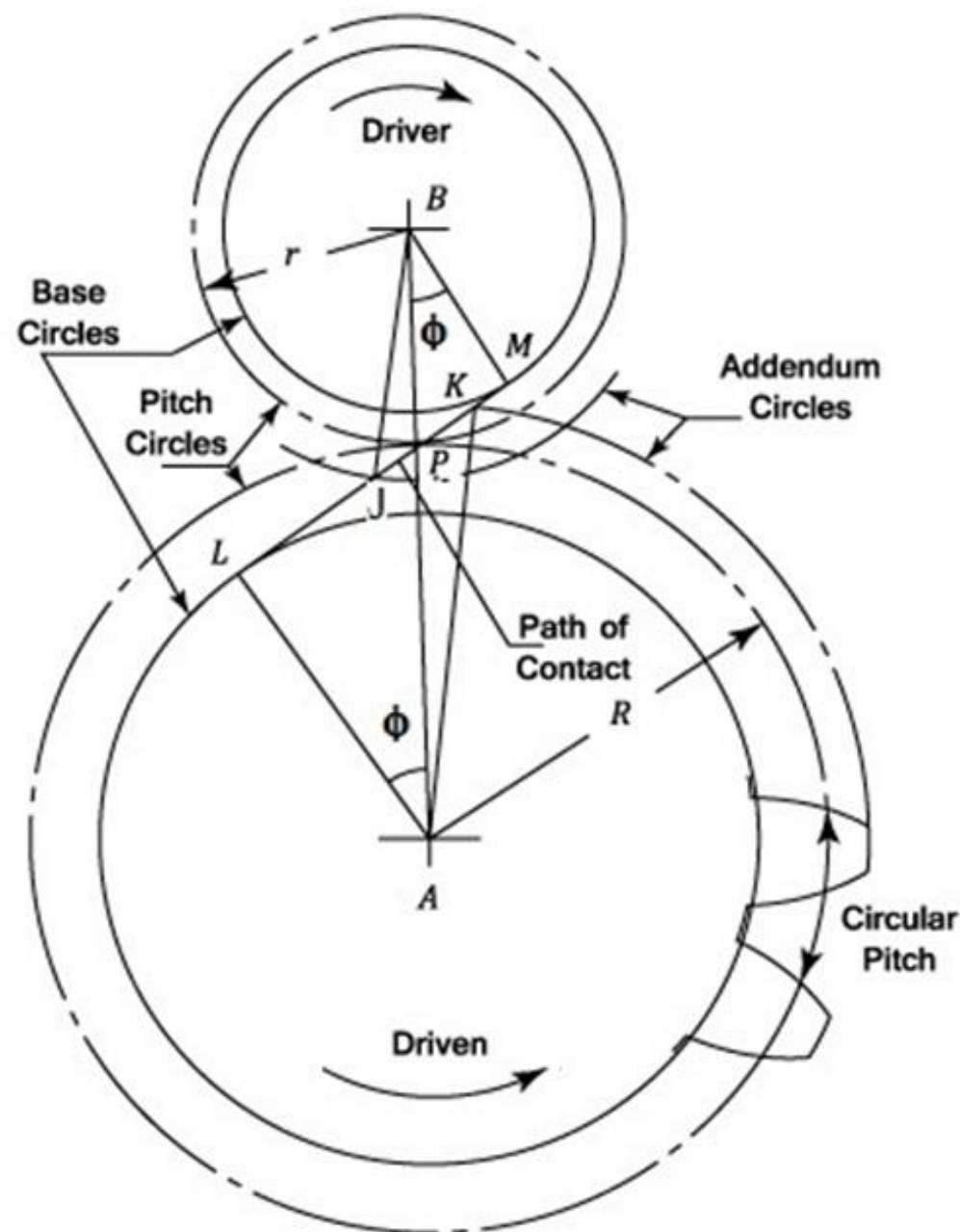
$$Z = \sqrt{(r_p + a)^2 - (r_p \cos \phi)^2} + \sqrt{(r_g + a)^2 - (r_g \cos \phi)^2} - C \sin \phi$$

OR:

$$Z = Z_1 + Z_2 - Z_3$$

Where:

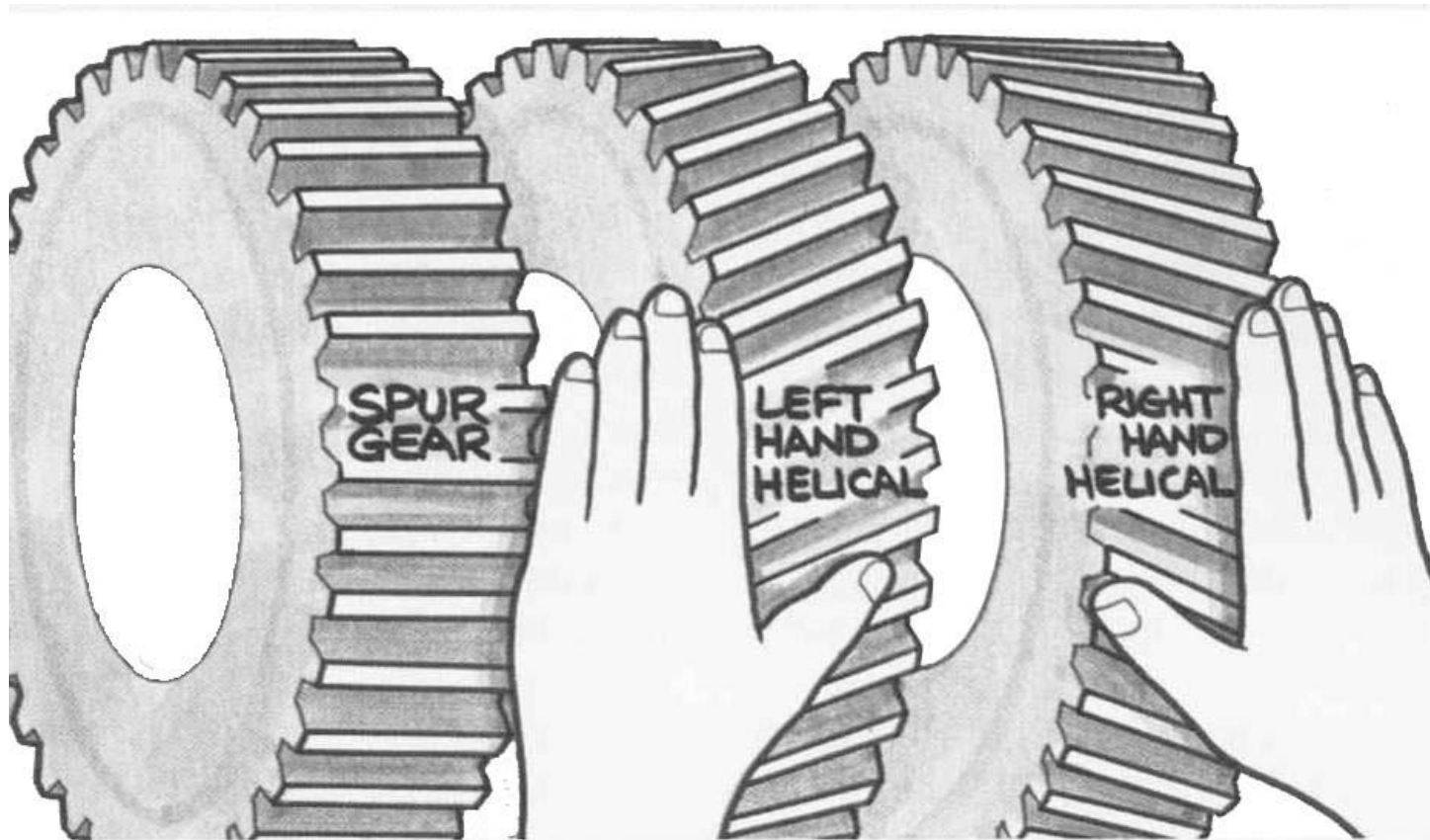
$$Z_1 = \sqrt{(r_p + a)^2 - (r_p \cos \phi)^2} \quad Z_2 = \sqrt{(r_g + a)^2 - (r_g \cos \phi)^2} \quad Z_3 = C \sin \phi$$

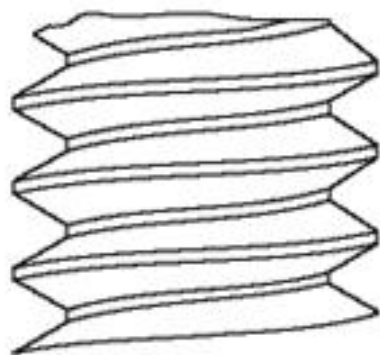


Left Hand

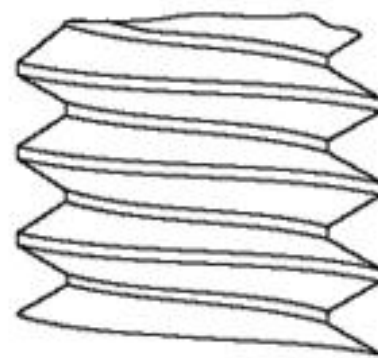


Right Hand

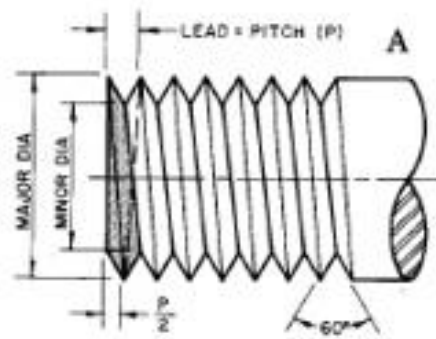




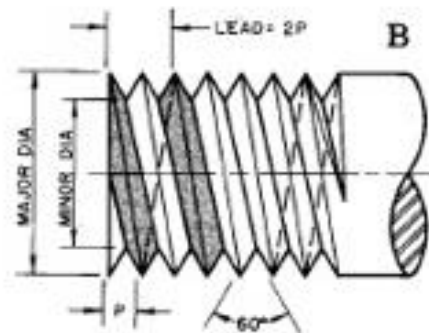
Right-Hand Thread



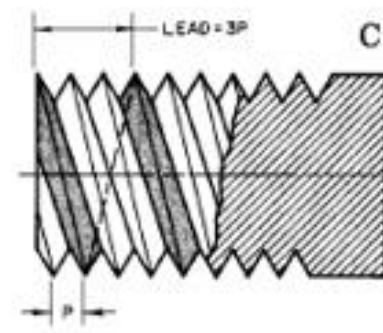
Left-Hand Thread



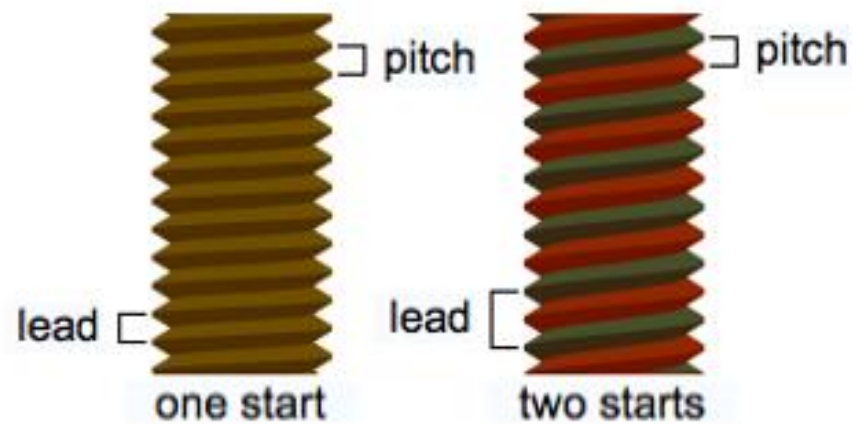
Single Thread

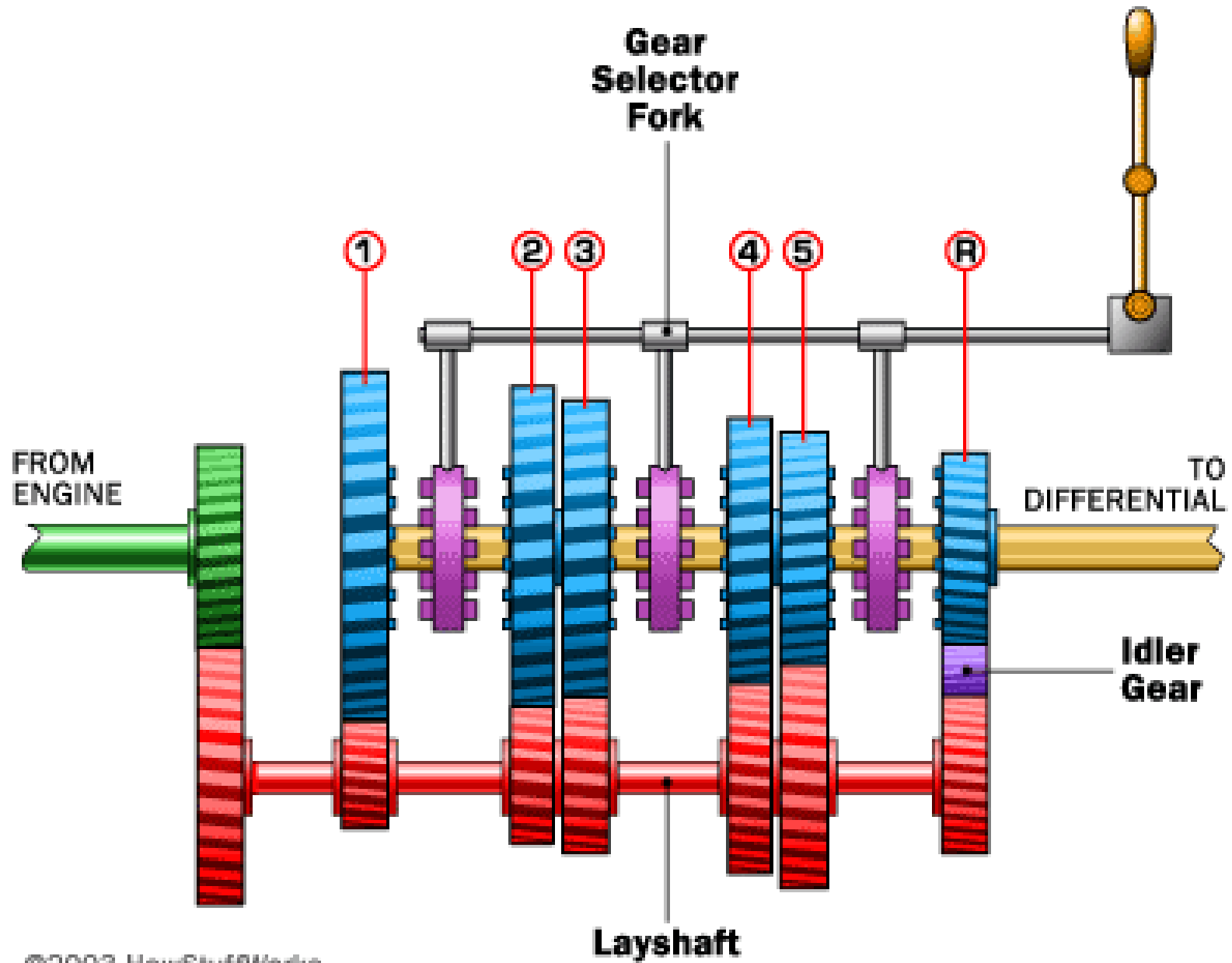


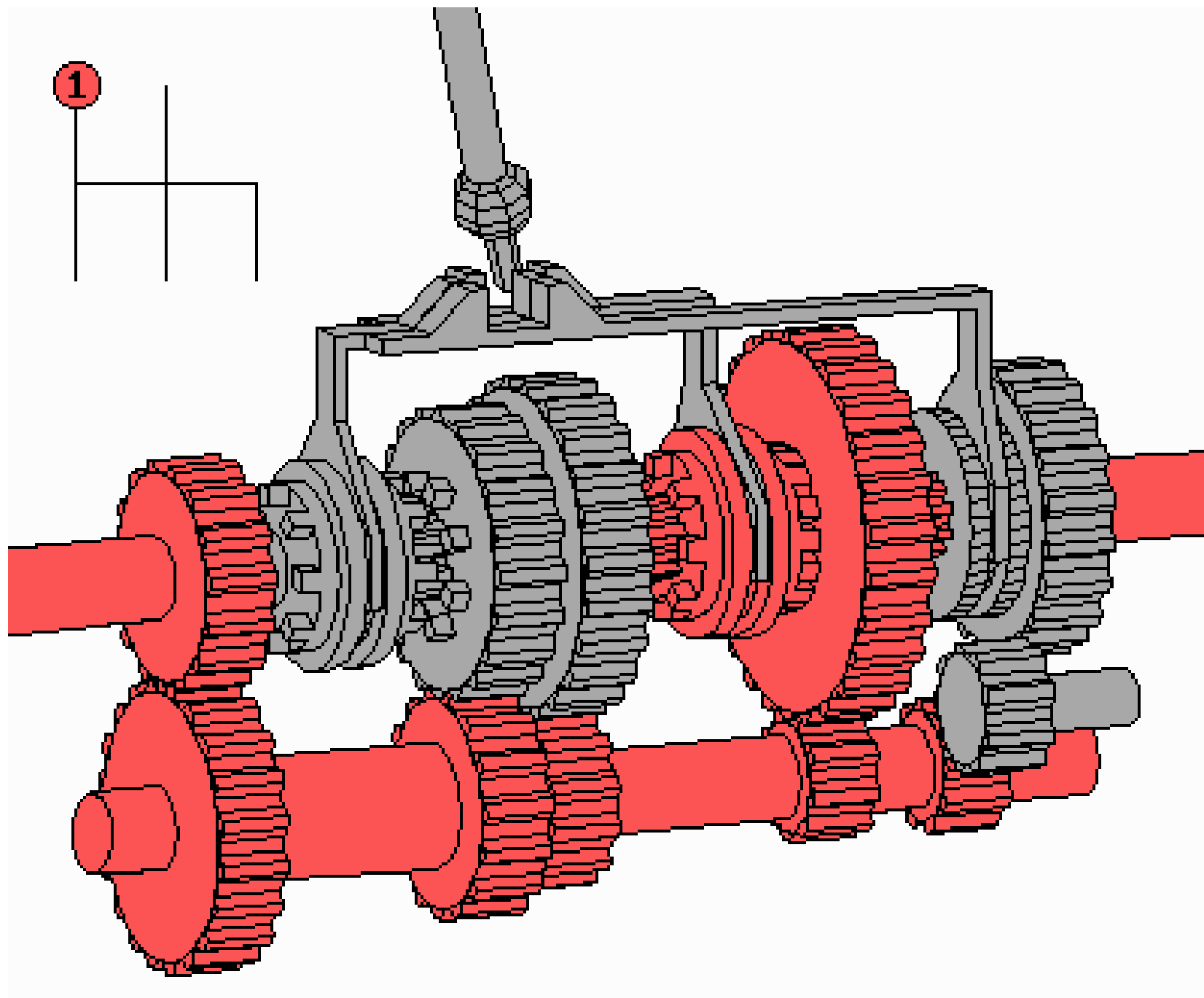
Double Thread

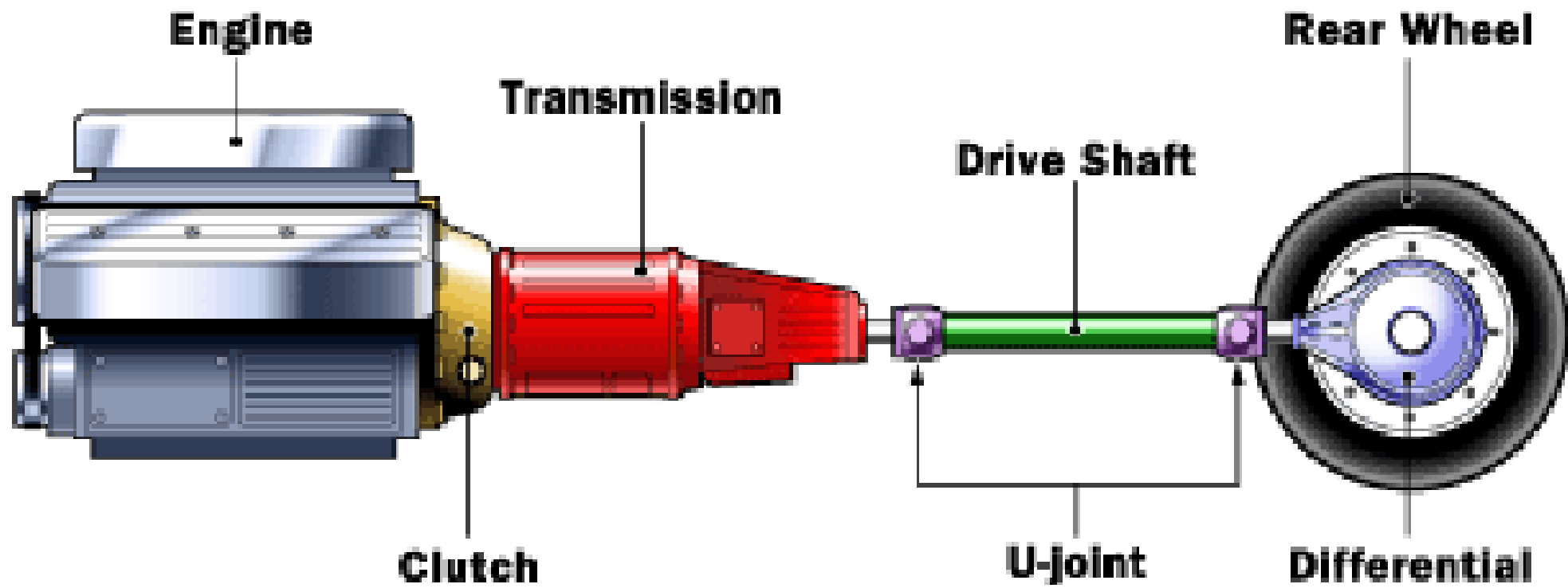


Triple Thread

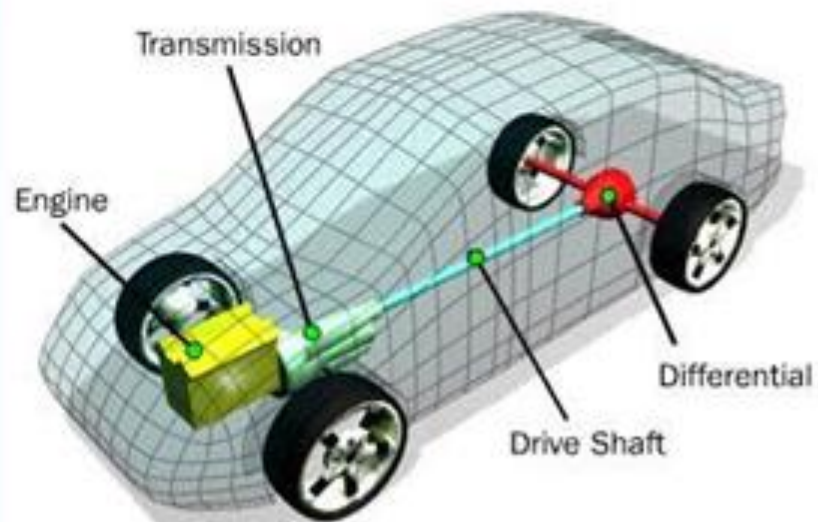






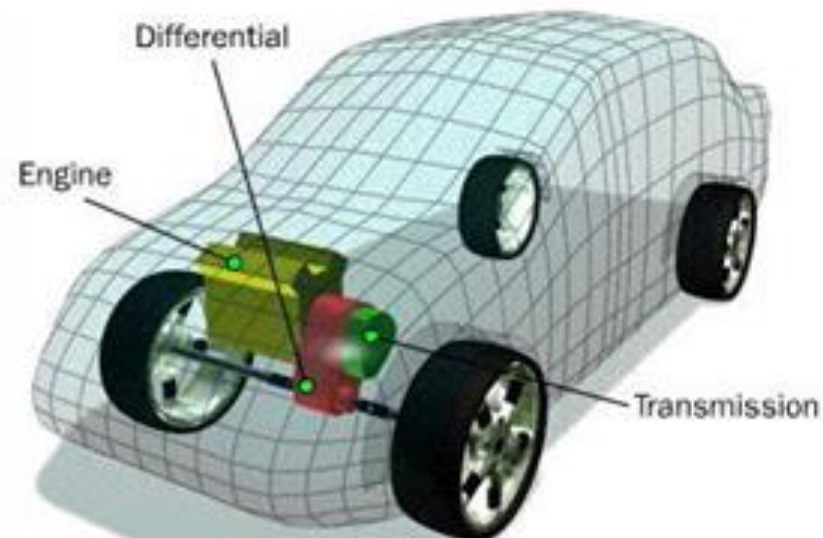


Rear-Wheel Drive



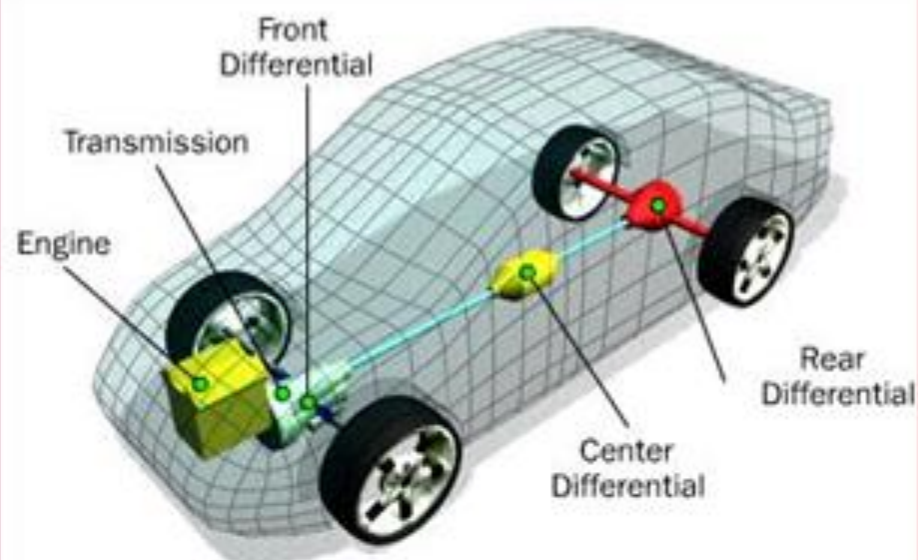
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Front-Wheel Drive



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All-Wheel Drive



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